



Principles of robot motion [theory, algorithms, and implementation /

Choset, Howie M.

MIT Press,
c2005

Monografía

This text reflects the great advances in the field that have taken place in the last ten years, including sensor-based planning, probabilistic planning, localization and mapping, and motion planning for dynamic and nonholonomic systems. Its presentation makes the mathematical underpinnings of robot motion accessible to students of computer science and engineering, relating low-level implementation details to high-level algorithmic concepts

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Título: Principles of robot motion [Recurso electrónico] theory, algorithms, and implementation Howie Choset ... [et al.].

Editorial: Cambridge, Mass. MIT Press c2005

Descripción física: 1 online resource (xix, 603 p.) ill

Tipo Audiovisual: Robots Motion Robots Mouvements Robotik. swd Robots Motion. fast Electronic books

Mención de serie: Intelligent robotics and autonomous agents

Nota general: "A Bradford book."

Bibliografía: Includes bibliographical references (p. [565]-596) and index

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ISBN: 0262033275 (alk. paper) 026225591X electronic bk.) 9780262255912 electronic bk.) 9780262033275 (alk. paper)

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Enlace a formato físico adicional: Print version:. Principles of robot motion. -- Cambridge, Mass. : MIT Press, c2005. (DLC) 2004044906

Punto acceso adicional serie-Título: Intelligent robotics and autonomous agents

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