

Motion Planning in Medicine: Optimization and Simulation Algorithms for Image-Guided Procedures [

Alterovitz, Ron

Springer Berlin Heidelberg, 2008

Monografía

The monograph written by Ron Alterovitz and Ken Goldberg combines ideas from robotics, physically-based modeling, and operations research to develop new motion planning and optimization algorithms for image-guided medical procedures. A challenge clinicians commonly face is compensating for errors caused by soft tissue deformations that occur when imaging devices or surgical tools physically contact soft tissue. A number of methods are presented which can be applied to a variety of medical procedures, from biopsies to anaesthesia injections to radiation cancer treatment. They can also be extended to address problems outside the context of medical robotics, including nonholonomic motion planning for mobile robots in field or manufacturing environments

https://rebiunoda.pro.baratznet.cloud: 28443/Opac Discovery/public/catalog/detail/b2FpOmNlbGVicmF0aW9uOmVzLmJhcmF0ei5yZW4vMTczMTAxMjUnderschildersch

Título: Motion Planning in Medicine: Optimization and Simulation Algorithms for Image-Guided Procedures Recurso electrónico-En línea] by Ron Alterovitz, Ken Goldberg

Editorial: Berlin, Heidelberg Springer Berlin Heidelberg 2008

Descripción física: XVI, 156p. 55 illus. digital

Tipo Audiovisual: Engineering Artificial intelligence Computer vision Systems theory Biomedical engineering Engineering Automation and Robotics Control Engineering Artificial Intelligence (incl. Robotics) Systems Theory, Control Biomedical Engineering Computer Imaging, Vision, Pattern Recognition and Graphics

Mención de serie: Springer tracts in advanced robotics 1610-7438 50

Documento fuente: Springer eBooks

Nota general: Engineering (Springer-11647)

Contenido: Introduction -- Physically-based Simulation of Soft Tissue Deformations -- Motion Planning in Deformable Soft Tissue with Applications to Needle Insertion -- Motion Planning in Deformable Soft Tissue with Obstacles with Applications to Needle Steering -- Motion Planning for Curvature-constrained Mobile Robots with Applications to Needle Steering -- The Stochastic Motion Roadmap: A Sampling-based Framework for Planning

with Motion Uncertainty -- Motion Planning for Radiation Sources during High-Dose-Rate Brachytherapy -- Conclusion

Restricciones de acceso: Accesible sólo para usuarios de la UPV

Tipo recurso electrónico: Recurso a texto completo

Detalles del sistema: Forma de acceso: Web

ISBN: 9783540692591
Autores: Goldberg, Ken

Entidades: SpringerLink (Servicio en línea)

Enlace a formato físico adicional: Printed edition 9783540692577

Punto acceso adicional serie-Título: Springer tracts in advanced robotics 1610-7438 50

Baratz Innovación Documental

• Gran Vía, 59 28013 Madrid

• (+34) 91 456 03 60

• informa@baratz.es